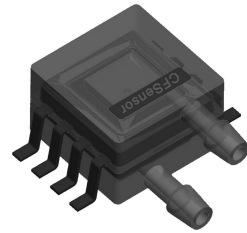


# XGZP6899D PRESSURE SENSOR

## FEATURES

- Wide Ranges: -100kPa...-0.5 ~ 0 ~ 0.5...700kPa(show in [Pressure Range Example](#))
- 2.5V ~ 5.5V Power Supply
- Differential Pressure Type
- For Non-corrosive Gas or Air
- Calibrated Digital Signal(I2C Interface)(Refer to XGZP6899A for Analog signal)
- Temp. Compensated: 0°C ~ +60°C(32°F ~ +140°F )
- Temperature Measurable
- Affordable Cost, Easy-to-use



✓ **RoHS**

## APPLICATIONS

- Medical&Healthcare
- Industrial&Automation
- Domestic Appliance
- Consumer Electronic
- Air Flow or Wind Pressure Measurement

## INTRODUCTION

XGZP6899D is a perfect silicon pressure sensor offering a ratiometric digital data(I2C interface) for reading differential pressure over the specified full scale pressure span.

The XGZP6899D incorporates a silicon piezoresistive pressure sensor chip and an interior signal-conditional Application Specific Integrated Circuit(ASIC) in a SOP8 package with two air vents, which can be mounted directly on a standard PCB.

The XGZP6899D is fully calibrated and temperature compensated for specified span, so XGZP6899D pressure sensor satisfy the perfect accuracy, which is designed for a wide range of application in medical care&health, home appliances, consumer electronic, industry, air flow measurement, IoT and other pneumatic devices/meters etc by utilizing a microcontroller or microprocessor with I2C interface.

XGZP6899D pressure sensor is for high volume application at an affordable cost and perfect performance. Customized calibration parameter (e.g.pressure range etc.) are available.

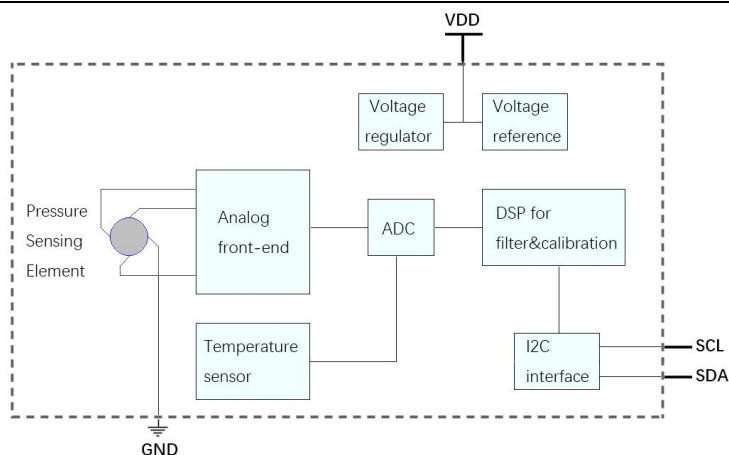
## PERFORMANCE SPECIFICATION

Unless otherwise specified, measurements were taken by 3.3Vdc with temperature of 25±1°C and humidity from 25% ~ 85 % RH.

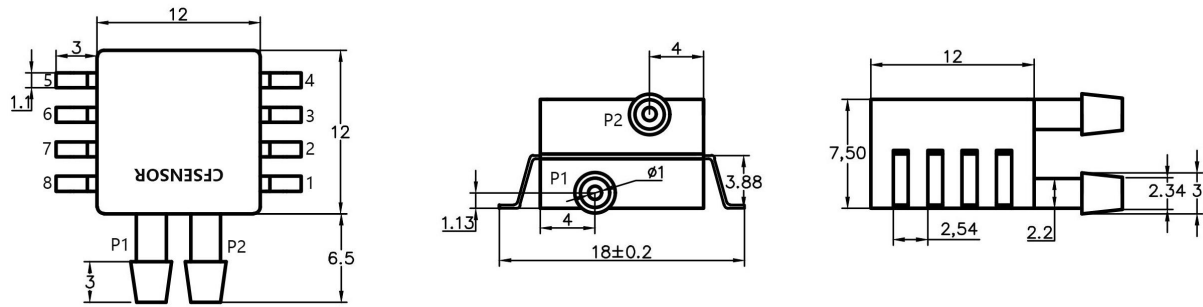
| CHARACTERISTIC                            |                              | MIN.                           | TYP.  | MAX  | UNIT |
|-------------------------------------------|------------------------------|--------------------------------|-------|------|------|
| Available Pressure Range <sup>①</sup>     |                              | <u>-100~-0.5 ~ 0 ~ 0.5~700</u> |       |      | kPa  |
| Power Supply <sup>②</sup>                 |                              | 2.5                            |       | 5.5  | Vdc  |
| Current Consumption                       | Operating Current            | -                              | 1.7   | -    | mA   |
|                                           | Standby Current              | -                              | 100   | -    | nA   |
| Output Resolution <sup>③</sup>            | Pressure                     | 24                             |       |      | Bit  |
|                                           | Temperature                  | 16                             |       |      | Bit  |
| Total Accuracy                            | 10kPa < Pressure ≤ 200kPa    | -                              | -     | ±2   | %FSS |
|                                           | Pressure ≤ 10kPa or > 200kPa | -                              | -     | ±2.5 | %FSS |
| Temperature Accuracy                      |                              | -1                             |       | 1    | °C   |
| Offset Drift after Soldering              |                              | -                              | -     | ±1   | %FSS |
| Long Term Stability(1000 hr, 25°C)        |                              | -                              | -     | ±0.5 | %FSS |
| Over Pressure <sup>④</sup>                | Pressure ≤ 5kPa              | -                              | 5X    | -    | FSS  |
|                                           | 5kPa < Pressure ≤ 200kPa     | -                              | 2.5X  | -    | FSS  |
| Burst Pressure <sup>④</sup>               | Pressure ≤ 5kPa              | -                              | 10X   | -    | FSS  |
|                                           | 5kPa < Pressure ≤ 200kPa     | -                              | 3X    | -    | FSS  |
| Pressure on P2 Port(Common mode pressure) |                              | -                              | -     | 1000 | kPa  |
| Compensation Temperature                  |                              | 0                              | -     | 60   | °C   |
| Operating Temperature                     |                              | -30                            | -     | 100  | °C   |
| Storage Temperature                       |                              | -40                            | -     | 125  | °C   |
| ESD Protection(Human Body Mode)           |                              | -                              | ±2000 | -    | V    |
| Response Time(combined conversion mode)   |                              | -                              | 5     | -    | mS   |

- ① The range cover all pressure ranges as shown as "PRESSURE RANGE EXAMPLE" list.
- ② Overload voltage(6.5Vdc above) or current(5mA above) may burn the IC and cause the sensor failure thoroughly.
- ③ The highest data bit as the signed number.
- ④ The indicated value is widespread value, contact CFsensor for more information on specific pressure range.

## BLOCK DIAGRAM



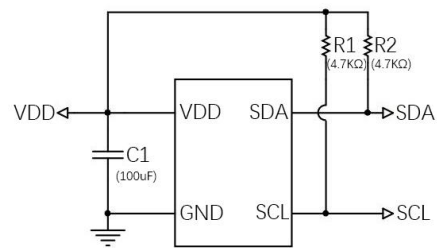
## DDIMENSION(Unit:mm Unspecified Tolerances:±0.1mm)



Note: Port 1(P1) as High pressure cavity, and Port 2(P2) as Low pressure cavity.

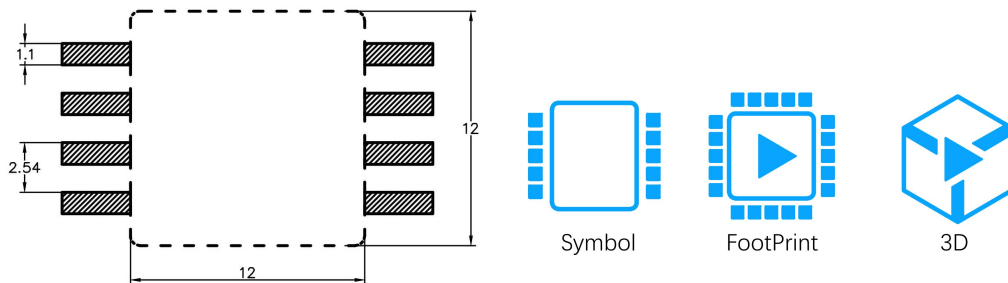
## PIN DEFINITION

| PIN2 | PIN3                                           | PIN4 | PIN6 | PIN1/5/7/8 |
|------|------------------------------------------------|------|------|------------|
| GND  | SCL                                            | SDA  | VDD  | N/C        |
| SCL  | The clock signal                               |      |      |            |
| NC   | Do not connect to external circuitry or ground |      |      |            |
| GND  | Ground                                         |      |      |            |
| VDD  | Voltage supply                                 |      |      |            |
| SDA  | Data signal(Send& Receive)                     |      |      |            |



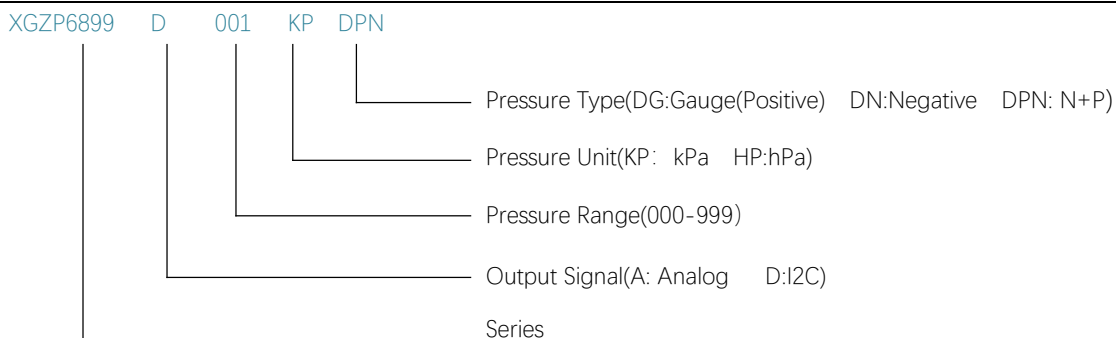
Recommended Application Circuit

## FOOTPRINT(Unit:mm)



NOTE: FOOTPRINT LAYOUT FOR REFERENCE ONLY CONTACT CFSensor FOR ABOVE FILE IF REQUIRED.

## ORDER GUIDE (100kPa=0.1MPa=1bar≈14.5PSI)



Note: Custom requirement or parameter, please consult CFSensor and comment custom code herewith Part number.

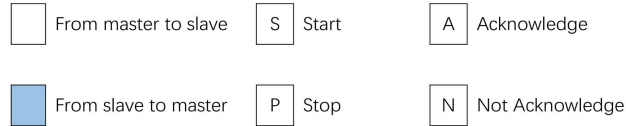
## PRESSURE RANGE EXAMPLE

Notes: 1. Unit conversion: 1000hPa=100kPa=0.1MPa=1000mbar=1bar≈750mmHg≈14.5PSI≈10mH<sub>2</sub>O;  
 2. Available for more custom pressure range e.g. -7 ~ 7kPa, , 0-250Pa etc.,.

| Pressure Range (kPa)                                                                                                         | Pressure Range (by other units)             | Part Number       |
|------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------|-------------------|
| -0.5 ~ 0.5                                                                                                                   | -5 ~ 5mbar / 500 ~ 500Pa                    | XGZP6899D005HPDPN |
| -1 ~ 1                                                                                                                       | -10 ~ 10mbar / -100 ~ 100mmH <sub>2</sub> O | XGZP6899D001KPDPN |
| -2.5 ~ 2.5                                                                                                                   | -25 ~ 25mbar / -250 ~ 250mmH <sub>2</sub> O | XGZP6899D025HPDPN |
| -5 ~ 5                                                                                                                       | -50 ~ 50mbar / -500 ~ 500mmH <sub>2</sub> O | XGZP6899D005KPDPN |
| -40 ~ 40                                                                                                                     | -400 ~ 400mbar / -300 ~ 300mmHg             | XGZP6899D040KPDPN |
| -100 ~ 100                                                                                                                   | -1 ~ 1bar / -14.5 ~ 14.5PSI                 | XGZP6899D100KPDPN |
| -100 ~ 200                                                                                                                   | -1 ~ 2bar / -14.5 ~ 29PSI                   | XGZP6899D200KPDPN |
| -100 ~ 0                                                                                                                     | -1 ~ 0bar / -14.5 ~ 0PSI                    | XGZP6899D100KPDN  |
| 0 ~ 1                                                                                                                        | 0 ~ 10mbar / 0 ~ 100mmH <sub>2</sub> O      | XGZP6899D010HPDG  |
| 0 ~ 2.5                                                                                                                      | 0 ~ 25mbar / 0 ~ 250mmH <sub>2</sub> O      | XGZP6899D025HPDG  |
| 0 ~ 5                                                                                                                        | 0 ~ 50mbar / 0 ~ 500mmH <sub>2</sub> O      | XGZP6899D005KPDG  |
| 0 ~ 10                                                                                                                       | 0 ~ 100mbar / 0 ~ 75mmHg                    | XGZP6899D010KPDG  |
| 0 ~ 20                                                                                                                       | 0 ~ 200mbar / 0 ~ 150mmHg                   | XGZP6899D020KPDG  |
| 0 ~ 40                                                                                                                       | 0 ~ 400mbar / 0 ~ 300mmHg                   | XGZP6899D040KPDG  |
| 0 ~ 50                                                                                                                       | 0 ~ 500mbar / 0 ~ 375mmHg                   | XGZP6899D050KPDG  |
| 0 ~ 100                                                                                                                      | 0 ~ 1bar / 0 ~ 14.5PSI                      | XGZP6899D100KPDG  |
| ★ Above P/N is example only, consult CFSensor whether required pressure range is under normal production before place order. |                                             |                   |

## I2C INTERFACE

I2C bus uses SCL and SDA as signal lines. Both lines are connected to VDD externally via pull-up resistors(Typ value:4.7k $\Omega$ ) so that they are pulled high when the bus is free. I2C device factory setting slave address: **0X6D**. The master device can communicate with the product using commands in the following format:



Write One Byte To One Register

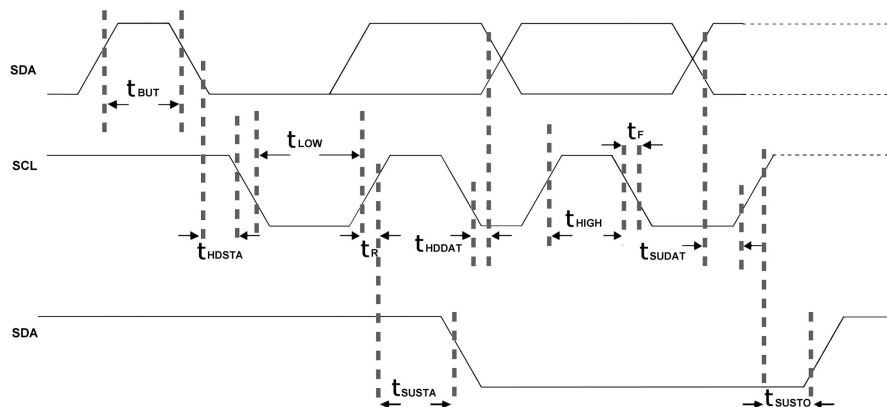


Read One Byte From One Register

## ELECTRICAL SPEC. OF I2C INTERFACE PIN

| Symbol             | Parameter                       | Min | Max | Unit |
|--------------------|---------------------------------|-----|-----|------|
| f <sub>scl</sub>   | Clock frequency                 |     | 400 | KHz  |
| t <sub>LOW</sub>   | SCL low pulse                   | 1.3 |     | us   |
| t <sub>HIGH</sub>  | SCL high pulse                  | 0.6 |     | us   |
| t <sub>SUDAT</sub> | SDA setup time                  | 0.1 |     | us   |
| t <sub>HDDAT</sub> | SDA hold time                   | 0.0 |     | us   |
| t <sub>SUSTA</sub> | Setup Time for a repeated start | 0.6 |     | us   |
| t <sub>HDSTA</sub> | Hold time for a start condition | 0.6 |     | us   |
| t <sub>SUSTO</sub> | Setup Time for a stop condition | 0.6 |     | us   |
| t <sub>BUF</sub>   | Time before a new transmission  | 1.3 |     | us   |

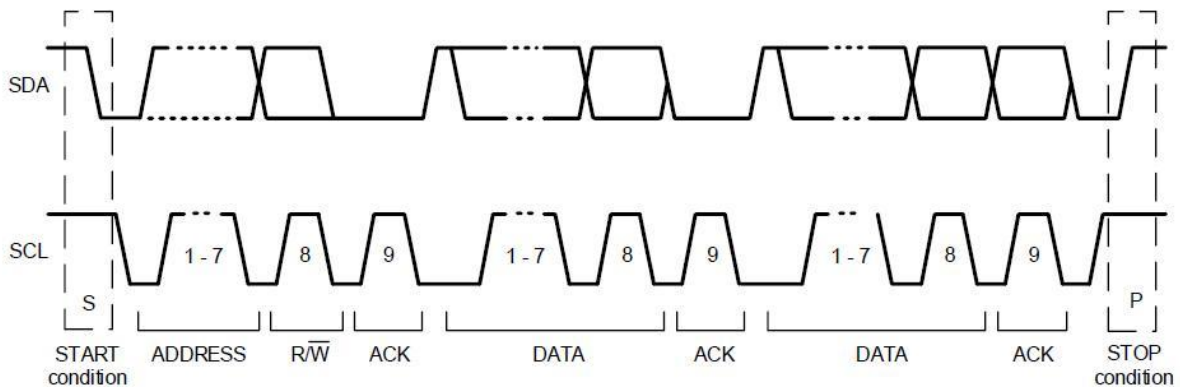
## I2C TIME DIAGRAM



The I2C interface protocol has special bus signal conditions. Start (S), stop (P) and binary data conditions are shown above. At start condition, SCL is high and SDA has a falling edge. Then the slave address is sent. After the 7 address bits, the direction control bit R/W selects the read or write operation. When a slave device recognizes that it is being addressed, it should acknowledge by pulling SDA low in the ninth SCL (ACK) cycle.

At stop condition, SCL is also high, but SDA has a rising edge. Data must be held stable at SDA when SCL is high. Data can change value at SDA only when SCL is low.

## I2C PROTOCOL



## REGISTER DESC.

| Add. | Desc.      | R/W | Bit7                     | Bit6 | Bit5        | Bit4 | Bit3       | Bit2                  | Bit1             | Bit0    | Default |
|------|------------|-----|--------------------------|------|-------------|------|------------|-----------------------|------------------|---------|---------|
| 0x06 | DATA_MSB   | R   | Pressure Data out<23:16> |      |             |      |            |                       |                  |         | 0x00    |
| 0x07 | DATA_CSB   | R   | Pressure Data out<15:8>  |      |             |      |            |                       |                  |         | 0x00    |
| 0x08 | DATA_LSB   | R   | Pressure Data out<7:0>   |      |             |      |            |                       |                  |         | 0x00    |
| 0x09 | TEMP_MSB   | R   | Temp Data out<15:8>      |      |             |      |            |                       |                  |         | 0x00    |
| 0x0A | TEMP_LSB   | R   | Temp Data out<7:0>       |      |             |      |            |                       |                  |         | 0x00    |
| 0x30 | CMD        | RW  | Sleep_time<7:4>          |      |             |      | Sco        | Measurement_ctrl<2:0> |                  |         | 0x00    |
| 0xA5 | Sys_config | RW  | Aout_config<7:4>         |      |             |      | LDO_config | Unipolar              | Data_out_control | Diag_on | OTP     |
| 0xA6 | P_config   | RW  | Input Swap               |      | Gain_P<5:3> |      |            | OSR_P<2:0>            |                  |         | OTP     |

### Reg0x06-Reg0x08 :

Pressure ADC data Register

### Reg0x09 & Reg0x0A :

Temperature ADC data Register

### Reg0x30 : Measurement Command Register

Sleep\_time<7:4>: 0000:0ms; 0001:62.5ms; 0010:125ms ;... 1111: 1s, only active during sleep mode conversion.

Sco: 1: Start of conversion, automatically come back to 0 after conversion ends (except sleep mode conversion).

Measurement\_control<2:0>:

010: indicate the combined conversion (namely a temperature conversion immediately followed by a pressure-signal conversion).

011: indicate a sleep mode conversion (periodically perform a combined conversion with an interval time of 'sleep\_time'),

**Reg0xA5**(configured at factory)

Aout\_config<7:4>: Analog output setting(recommending reserve default value)

LDO\_config: 0: set with 1.8V;

1: set with 3.6V.

Polarity: 0: ADC output in bipolar format(signed binary),

1: ADC output in unipolar format. (Unsigned binary, Only take effect when 'raw\_data\_on' = 1)

Raw\_data\_on: 0: output calibrated data(as default value),

1: output ADC raw data.

Diag\_on: 1, Enable diagnosis function(default).

**Reg0xA6**(configured at factory)

Input Swap: Swap VINP and VINN inside the ASIC

Gain\_<5:3>: set the gain of the sensor signal conversion channel. 000: gain=1, 001: gain=2, 010: gain=4, 011: gain=8, 100: gain=16, 101: gain=32, 110: gain=64, 111: gain=128.

OSR\_P<2:0>: set the over sampling ratio of the sensor signal conversion channel. 000:1024X, 001:2048X, 010:4096X, 011:8192X, 100:256X, 101:512X, 110:16384X, 111:32768X.

## READ OPERATION

As the following instruction sequences for reading data:

(Only for combined conversion (namely a temperature conversion immediately followed by a pressure-signal conversion))

1. Send instructions 0x0A(combined conversion mode command) to 0x30 register to start conversion.
2. Read the 0x30 register address. If Sco bit is 0, signify the acquisition end, the data can be read.  
(Or, skip above step and delay 20mS and to read data directly)
3. Read 0x06, 0x07, 0x08 register address data to form a 24-bit AD value (pressure data AD value); Read 0x09, 0x0A register address data to form a 16-bit AD value (temperature data AD value)

### Read Pressure

The total pressure output value which include 0x06, 0x07 and 0x08 registers are 24 bits. The highest position is the signed bit, and the value is "0", it represents "positive" pressure; The symbol digit value is "1", it represents "negative" pressure.

Pressure\_ADC value: = (Pressure 3rd Byte [23:16] x 65536+Pressure 2nd Byte [15:8] x 256 + Pressure1st Byte [7:0])

Note: 1 Pressure 3rd Byte [23:16] is the hexadecimal value read out by REG0x06 and need convert into decimal value;

2 Pressure 2nd Byte [15:8] is the hexadecimal value read out by REG0x07 and need convert into decimal value;

3 Pressure 1st Byte [7:0] is the hexadecimal value read out by REG0x08 and need convert into decimal value.

For Pressure conversion formula are as follows:

The highest bit is "0", which means positive pressure, then  $\text{Pressure} = \text{Pressure\_ADC}/k$ ;

The highest bit is "1", which means negative pressure, then  $\text{Pressure} = (\text{Pressure\_ADC} - 2^{24})/k$ ;

| Pressure Range(kPa)                    | K value | Sensor Pressure Range Example             |
|----------------------------------------|---------|-------------------------------------------|
| $130 < \text{Pressure Range} \leq 260$ | 32      | 0~200kPa; -100~200kPa...                  |
| $65 < \text{Pressure Range} \leq 130$  | 64      | 0~100kPa; -100~100kPa; -100~0kPa...       |
| $32 < \text{Pressure Range} \leq 65$   | 128     | 0~40kPa; -40~40kPa; -40~0kPa...           |
| $16 < \text{Pressure Range} \leq 32$   | 256     | 0~20kPa; -20~20kPa; -20~0kPa; -30~0kPa... |
| $8 < \text{Pressure Range} \leq 16$    | 512     | 0~10kPa; -10~10kPa; -10~0kPa...           |
| $4 < \text{Pressure Range} \leq 8$     | 1024    | 0~5kPa; -5~5kPa; -1~1PSI...               |
| $2 \leq \text{Pressure Range} \leq 4$  | 2048    | 0~2.5kPa; -2.5~2.5kPa...                  |
| $1 \leq \text{Pressure Range} < 2$     | 4096    | 0~1kPa; -1~1kPa; -0.5~0.5kPa...           |

Note:

1. the unit is Pa (default value). If need to display other units, fill the corresponding factor in the conversion formula;
2. the K value is selected according to the absolute value span from 0kPa to the Max. pressure point. eg for -100 ~ 100kPa or -100 ~ 0kPa or 0 ~ 100kPa, the absolute value span from 0kPa to the Max. Pressure value. is 100kPa, so the K value is 64.

## Read Temperature

The bits of temperature output values in the 0x09 and 0x0A registers are 16 bits, the highest is the sign bit.

The sign digit value is "0" when it represents "positive" temperature, and the sign digit value is "1" when it represents "negative" temperature.

Supposing if the decimal values of REG0x09 and REG0x0A readout are X, Y,

For Temperature ADC value and conversion formula are as:

Temperature AD value:  $N = X * 256 + Y$

If  $n < 2^{15}$ , Temperature is positive value, actual temperature  $T = N/256$ ; (°C).

If  $n > 2^{15}$ , Temperature is negative value, actual temperature value =  $(N - 2^{16}) / 256$ ; (°C)

## PACKING INFORMATION

### Tube Packing

|          |                |                    |                 |
|----------|----------------|--------------------|-----------------|
| Packing  | Plastic Tube   | Inner Box          | Note            |
| Quantity | 27PCS per tube | 648pcs(24pcs tube) | Anti-static bag |

Note: The sensor should be stored in an ESD protective container before using them.

## OVERALL NOTES

Unless otherwise specified, following notes are general attention or presentation for all products from CFsensor.

### Mounting

The following steps is for transmitting the air pressure to sensor after sensor soldering on PCB.

- ▼ For some sensors that come with inlet tube, select the flexible pipe to suit the pressure inlet that is firm enough to prevent the pressure leaks.
- ▼ Atmosphere hole (for Gauge type sensors) and Inlet pipe/hole can't be blocked with gel or glue etc...
- ▼ Avoiding excessive external force operation

### Soldering

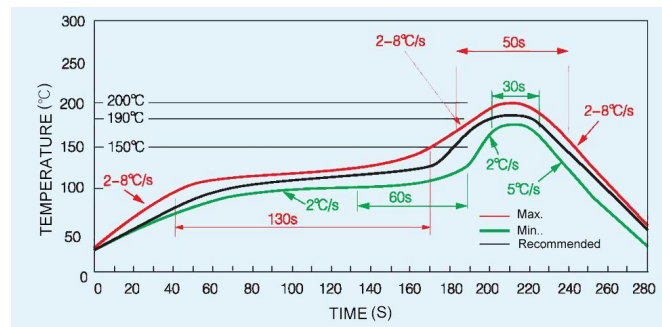
Due to its small size, the thermal capacity of the pressure sensor is low. Therefore, take steps to minimize the effects of external heat. Damage and changes to characteristics may occur due to heat deformation. Use a non-corrosive resin type of flux. Since the pressure sensor is exposed to the atmosphere, do not allow flux to enter inside.

#### ▼ Manual soldering

- Raise the temperature of the soldering tip to 190°C max. and solder within 5 seconds.
- The sensor output may vary if the load is applied on the terminal during soldering.
- Keep the soldering tip clean.

#### ▼ Reflow soldering (SMD Terminal)

- Considering the thermal effect on offset drift for the low pressure range, the Low Temperature Soldering curve are recommended as below.



- Self alignment may not always work as expected, therefore, please carefully the position of the terminals and pattern.
- The temperature of the profile is assumed to be a value measured with the printed wiring board of the terminal neighborhood.
- Please evaluate solderability under the actual mounting conditions since welding and deformation of the pressure inlet port may occur due to heat stress depending on equipments or conditions.
- ▼ Rework soldering
  - Complete rework at a time.
  - Use a flattened soldering tip when performing rework on the solder bridge. Do not add the flux.
  - Keep the soldering tip below the temperature described in the specifications.
- ▼ Avoid drop and rough handling as excessive force may deform the terminal and damage soldering characteristics.
- ▼ Keep the circuit board warpage within 0.05 mm of the full width of the sensor.
- ▼ After soldering, do not apply stress on the soldered part when cutting or bending the circuit board.
- ▼ Prevent human hands or metal pieces from contacting with the sensor terminal. Such contact may cause anomalous outlets as the terminal is exposed to the atmosphere.

▼ After soldering, prevent chemical agents from adhering to the sensor when applying coating to avoid insulation deterioration of the circuit board.

#### Connecting

▼ Correctly wire as in the connection diagram. Reverse connection may damage the product and degrade the performance.

▼ Do not use idle terminals(N/C) to prevent damages to the sensor.

#### Cleaning

▼ Since the pressure sensor is exposed to the atmosphere, do not allow cleaning fluid to enter inside from atmosphere hole (for Gauge type sensors) and inlet pipe.

▼ Avoid ultrasonic cleaning since this may cause breaks or disconnections in the wiring.

#### Environment

▼ Please avoid using or storing the pressure sensor in a place exposed to corrosive gases (such as the gases given off by organic solvents, sulfurous acid gas, hydrogen sulfides, etc.) which will adversely affect the performance of the pressure sensor chip.

▼ Since this pressure sensor itself does not have a water-proof construction(even available media can be liquid), please do not use the sensor in a location where it may be sprayed with water, etc.

▼ Avoid using the pressure sensors in an environment where condensation may form. Furthermore, its output may fluctuate if any moisture adhering to it freezes.

▼ The pressure sensor is constructed in such a way that its output will fluctuate when it is exposed to light. Especially when pressure is to be applied by means of a transparent tube, take steps to prevent the pressure sensor chip from being exposed to light.

▼ Avoid using pressure sensor where it will be susceptible to ultrasonic or other high-frequency vibration.

▼ Keeping the sensors sealed in static shielding bags with an oxygen-free condition and use the sensor as soon as possible once unfold the package, because the sensors' PINs may be oxidated a bit under atmosphere environment(slight oxidation wouldn't affect soldering and performance)

#### More Precautions

▼ That using the wrong pressure range or mounting method may result in accidents.

▼ The only direct pressure medium you can use is non-corrosive gas or air as illuminated above(Note: some sensors are compatible with liquid media). The use of other media, in particular, corrosive gases and liquid (organic solvent based, sulfurous acid based, and hydrogen sulfide based, etc.) or contains foreign substances will cause malfunction and damage. Please do not use them and check with CFSensor.

▼ The pressure sensor is positioned inside the pressure inlet. Never poke wires or other foreign matter through the pressure inlet since they may damage the sensor or block the inlet. Avoid use when the atmospheric pressure inlet(only for Gauge type pressure sensor) is blocked.

▼ Use an operating pressure which is within the rated pressure range. Using a pressure beyond this range may cause damage.

▼ Since static charge can damage the pressure sensor, bear in mind the following handling precautions.

☉ When storing the pressure sensor, use a conductive material to short the pins or wrap the entire sensor in aluminum foil. Common plastic containers should not be used to store or transport the sensor since they readily become charged.

☉ When using the pressure sensor, all the charged articles on the bench surface and the work personnel should be grounded so that any ambient static will be safely discharged.

▼ Based on the pressure involved, give due consideration to the securing of the pressure sensor.

### 【 SAFETY NOTES 】

Using these sensors products may malfunction due to external interference and surges, therefore, please confirm the performance and quality in actual use. Just in case, please make a safety design on the device (fuse, circuit breaker, such as the installation of protection circuits, multiple devices, etc.), so it would not harm life, body, property, etc even a malfunction occurs. To prevent injuries and accidents, please be sure to observe the following items:

- The driving current and voltage should be used below the rated value.
- Please follow the terminal connection diagram for wiring. Especially for the reverse connection of the power supply, it will cause an accident due to circuit damage such as heat, smoke, fire, etc.
- In order to ensure safety, especially for important uses, please be sure to consider double safety circuit configuration.
- Do not apply pressure above the maximum applied pressure. In addition, please be careful not to mix foreign matter into the pressure medium. Otherwise, the sensor will be discarded, or the media will blow out and cause an accident.
- Be careful when fixing the product and connecting the pressure inlet. Otherwise, accidents may occur due to sensor scattering and the blowing out of the media.
- If the sensor come with sharp PIN, please be careful not to hurt your body when using it.

### 【 WARRANTY 】

The information in this sheet has been carefully reviewed and is believed to be accurate; however, no responsibility is assumed for inaccuracies. Furthermore, this information does not convey to the purchaser of such devices any license under the patent rights to the manufacturer. CFSensor reserves the right to make changes without further notice to any product herein. CFSensor makes no warranty, representation or guarantee regarding the suitability of its product for any particular purpose, nor does CFSensor assume any liability arising out of the application or use of any product or circuit and specifically disclaims any and all liability, including without limitation consequential or incidental damages. Typical parameters can and do vary in different applications. All operating parameters must be validated for each customer application by customer's technical experts. CFSensor does not convey any license under its patent rights nor the rights of others.

### 【 CONTACT 】

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North America || Europe || Southeast Asia || Middle East || Latin America

## READ CODE(C51 Example)

---

```
#include <reg52.h>
#include <math.h>
#define DELAY_TIME 600
#define TRUE 1
#define FALSE 0
#define uchar unsigned char
#define uint unsigned int

//----define IIC SCL, SDA port----
sbit SCL = P1 ^ 7;
sbit SDA = P1 ^ 6;

//----delay time_us----
void DELAY(uint t)
{
    while (t != 0)
        t--;
}

//----IIC START CONDITION----
void I2C_Start(void)
{
    SDA = 1;    //SDA output high
    DELAY(DELAY_TIME);
    SCL = 1;
    DELAY(DELAY_TIME); //SCL output high
    SDA = 0;
    DELAY(DELAY_TIME);
    SCL = 0;
    DELAY(DELAY_TIME);
}

//----IIC STOP CONDITION----
void I2C_Stop(void)
{
    SDA = 0;    //SDA OUTPUT LOW
    DELAY(DELAY_TIME);
    SCL = 1;
    DELAY(DELAY_TIME);
    SDA = 1;
```

```
    DELAY(DELAY_TIME);  
    SCL = 0;    //SCL OUTPUT LOW  
    DELAY(DELAY_TIME);  
}
```

```
//----IIC SEND DATA "0"----
```

```
void SEND_0(void)
```

```
{  
    SDA = 0;  
    DELAY(DELAY_TIME);  
    SCL = 1;  
    DELAY(DELAY_TIME);  
    SCL = 0;  
    DELAY(DELAY_TIME);  
}
```

```
//----IIC SEND DATA "1"----
```

```
void SEND_1(void)
```

```
{  
    SDA = 1;  
    DELAY(DELAY_TIME);  
    SCL = 1;  
    DELAY(DELAY_TIME);  
    SCL = 0;  
    DELAY(DELAY_TIME);  
}
```

```
//----Check SLAVE's Acknowledge----
```

```
bit Check_Acknowledge(void)
```

```
{  
    SDA = 1;  
    DELAY(DELAY_TIME);  
    SCL = 1;  
    DELAY(DELAY_TIME / 2);  
    F0 = SDA;  
    DELAY(DELAY_TIME / 2);  
    SCL = 0;  
    DELAY(DELAY_TIME);  
    if (F0 == 1)  
        return FALSE;  
    return TRUE;  
}
```

```
//----Write One Byte of Data----
```

```
void Writel2CByte(uchar b) reentrant
```

```
{
    char i;
    for (i = 0; i < 8; i++)
        if ((b << i) & 0x80)
            SEND_1();
        else
            SEND_0();
}
```

```
//----Read One Byte of Data----
```

```
uchar Readl2CByte(void) reentrant
```

```
{
    char b = 0, i;
    for (i = 0; i < 8; i++)
    {
        SDA = 1;
        DELAY(DELAY_TIME);
        SCL = 1;
        DELAY(DELAY_TIME);
        F0 = SDA;
        DELAY(DELAY_TIME);
        SCL = 0;
        if (F0 == 1)
        {
            b = b << 1;
            b = b | 0x01;
        }
        else
            b = b << 1;
    }
    return b;
}
```

```
//----write One Byte of Data,Data from MASTER to the SLAVER----
```

```
void Write_One_Byte(uchar addr, uchar thedata) //Write "thedata" to the SLAVER's address of "addr"
```

```
{
    bit acktemp = 1;
    I2C_Start(); //IIC START
    Writel2CByte(0x6D << 1 + 0); //IIC WRITE operation, SLAVER address bit: 0x6D
    acktemp = Check_Acknowledge(); //check the SLAVER
}
```

```
    Writel2CByte(addr);          //address
    acktemp = Check_Acknowledge();
    Writel2CByte(thedata);       //thedata
    acktemp = Check_Acknowledge();
    I2C_Stop(); //IIC STOP
}

//----Read One Byte of Data,Data from SLAVER to the MASTER----
uchar Read_One_Byte(uchar addr)
{
    bit acktemp = 1;
    uchar mydata;

    I2C_Start();
    Writel2CByte(0x6D << 1 + 0);    //IIC WRITE operation, SLAVER address bit: 0x6D
    acktemp = Check_Acknowledge();
    Writel2CByte(addr);
    acktemp = Check_Acknowledge();
    I2C_Start();
    Writel2CByte(0x6D << 1 + 1);    //IIC READ operation, SLAVER address bit: 0x6D
    acktemp = Check_Acknowledge();
    mydata = Readl2CByte();
    I2C_Stop();
    return mydata;
}

//----Delay_ms----
void Delay_xms(uint x)
{
    uint i, j;
    for (i = 0; i < x; i++)
        for (j = 0; j < 112; j++)
            ;
}

//----The main function----
void main(void)
{
    uchar pressure_H, pressure_M, pressure_L, temperature_H, temperature_L;
    //temporary variables of pressure and temperature
    long int pressure_adc, temperature_adc;
    //The value of pressure and temperature converted by the sensor's ADC
```

```
long float pressure, temperature;
//The calibrated value of pressure and temperature
Delay_xms(1000);    //delay 1000ms

while (1)
{
    Write_One_Byte(0x30, 0x0A);
    //indicate a combined conversion (once temperature conversion immediately followed by once sensor signal
    conversion)
    //more measurement method, check Register 0x30
    while ((Read_One_Byte(0x30) & 0x08) > 0); //Judge whether Data collection is over, if above action has no
    response, delete that command and execute this command as: Delay_xms(20);

    pressure_H = Read_One_Byte(0x06);
    pressure_M = Read_One_Byte(0x07);
    pressure_L = Read_One_Byte(0x08);
    // Read ADC output Data of Pressure
    pressure_adc = pressure_H * 65536 + pressure_M * 256 + pressure_L;
    //Compute the value of pressure converted by ADC

    if (pressure_adc > 8388608)
        pressure = (pressure_adc - 16777216) / K; //unit is Pa, select appropriate K value according to pressure range.
    else
        pressure = pressure_adc / K; //unit is Pa, select appropriate K value according to pressure range.
    //The conversion formula of calibrated pressure, its unit is Pa

    temperature_H = Read_One_Byte(0x09);
    temperature_L = Read_One_Byte(0x0A);
    //Read ADC output data of temperature
    temperature_adc = temperature_H * 256 + temperature_L;
    //Compute the value of temperature converted by ADC
    temperature = (temperature_adc - 65536) / 256;    //unit is °C
    else
        temperature = temperature_adc / 256;    //unit is °C
    //The conversion formula of calibrated temperature, its unit is Centigrade

    Delay_xms(100); //delay 100ms
}
}
```